



UNIVERSITY OF COPENHAGEN

Likelihood Inference for SDE-models

with applications in Biology and Geophysics

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Likelihood function for discrete time observations

$$dX_t = b(X_t; \theta)dt + \sigma(X_t; \theta)dW_t \quad \theta \in \Theta \subseteq \mathbb{R}^p$$

X , b and W d -dimensional, σ $d \times d$ -matrix

Data: $X_{t_0}, \dots, X_{t_n}$, $0 = t_0 < \dots < t_n$

Likelihood-function:

$$L_n(\theta) = \prod_{i=1}^n p(\Delta_i, X_{t_{i-1}}, X_{t_i}; \theta), \quad \Delta_i = t_i - t_{i-1}$$

$$X_\Delta | X_0 = x \sim p(\Delta, x, \cdot; \theta)$$



Bayesian estimation for diffusion processes

$$dX_t = \alpha(X_t; \theta)dt + \sigma(X_t)dW_t$$

Data: $D = (X_{t_0}, \dots, X_{t_n})$, $t_0 = 0$

Partial observation of $\mathbf{X}_{t_n} = (X_t)_{0 \leq t \leq t_n}$



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Gibbs sampler

1. Draw θ from the prior distribution
2. Simulate a sample path $\mathbf{X}_{t_n}$ conditionally on θ and D
3. Draw θ conditionally on $\mathbf{X}_{t_n}$ and D
4. GO TO 2



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Diffusion bridge: A solution of the SDE in the interval $[0, T]$ such that $X_0 = a$ and $X_T = b$ is called an (a, b, T) -bridge.

Assume that the process X is ergodic

Simple bridge simulation: Bladt and Sørensen (Bernoulli 2014, 2021)



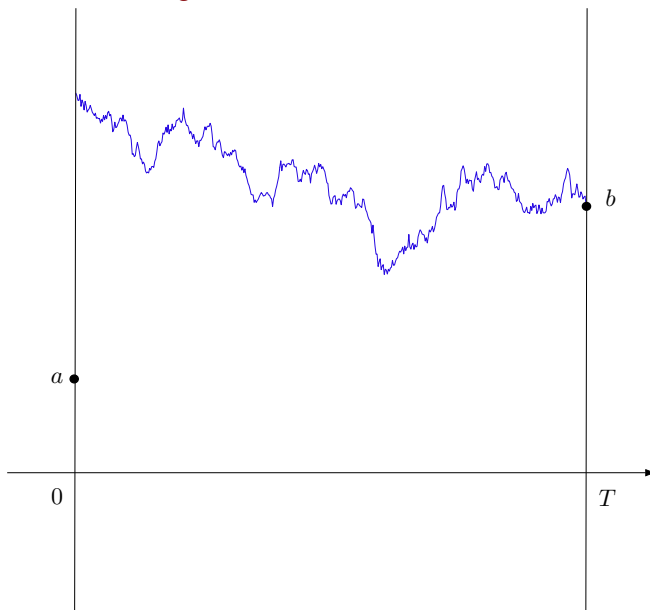
Diffusion bridge simulation

An incomplete list of other papers

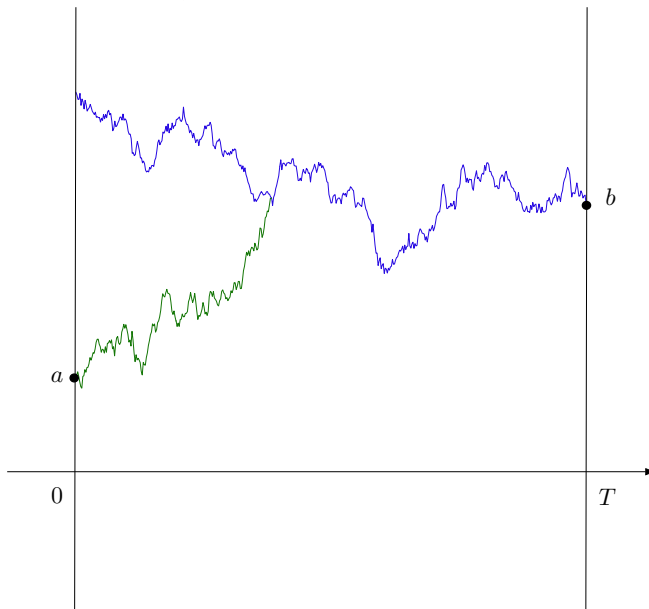
- Durham and Gallant (2002)
- Delyon and Hu (2006)
- Beskos, Papaspiliopoulos and Roberts (2006, 2007)
- Golightly and Wilkinson (2008)
- Hairer, Stuart and Voss (2009)
- Chen and Huang (2013)
- Pollock, Johansen and Roberts (2016)
- Schauer, van der Meulen and van Zanten (2017)
- van der Meulen and Schauer (2017)
- Whitaker, Golightly, Boys and Sherlock (2017)



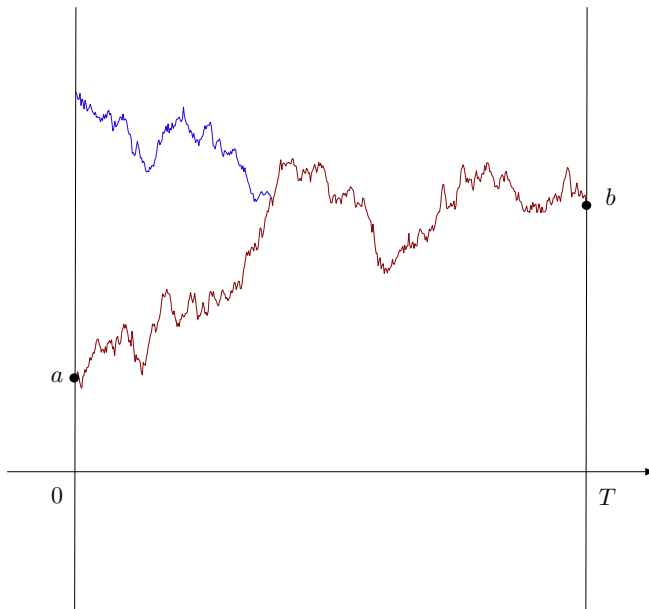
1D Diffusion bridge simulation



1D Diffusion bridge simulation



1D Diffusion bridge simulation



Approximate diffusion bridge simulation

$$dX_t^i = \alpha(X_t^i)dt + \sigma(X_t^i)dW_t^i, \quad X_0^1 = a \quad \text{and} \quad X_0^2 = b$$

W^1 and W^2 independent standard Wiener processes

Define $\tau = \inf\{0 \leq t \leq T | X_t^1 = X_{T-t}^2\}$ ($\inf \emptyset = +\infty$) and

$$Z_t = \begin{cases} X_t^1 & \text{if } 0 \leq t \leq \tau \\ X_{T-t}^2 & \text{if } \tau < t \leq T. \end{cases}$$

Theorem

The distribution of $\{Z_t\}_{0 \leq t \leq T}$ conditional on the event $\{\tau \leq T\}$ equals the distributions of an (a, b, T) -bridge conditional on the event that the bridge is hit by an independent stationary diffusion with the same stochastic differential equation as X .



Approximate diffusion bridge simulation

$$Z_t = \begin{cases} X'_t & \text{if } 0 \leq t \leq \tau \\ \bar{X}_t & \text{if } \tau < t \leq T, \end{cases}$$

Theorem

The density of Z on the canonical space $C_{a,b}([0, T])$:

$$f_{appr}(x) = f(x)\pi_T(x)/\pi_T$$

- $C_{a,b}([0, T])$: the continuous functions on $[0, T]$ from a to b
- f is the density of an (a, b, T) -diffusion bridge
- $\pi_T(x)$: probability that the sample path x is hit by an independent stationary diffusion
- π_T : probability that an (a, b, T) -diffusion bridge is hit by an independent stationary diffusion



Metropolis-Hastings algorithm: exact bridge

Simulate an initial approximate (a, b, T) -diffusion bridge, $X^{(0)}$, set $k = 1$.

(1) Propose a new sample paths by simulating an approximate (a, b, T) -diffusion bridge $X^{(k)}$

(2) Accept the proposed diffusion bridge with probability

$$\min \left(1, \frac{f(X^{(k)})f_{appr}(X^{(k-1)})}{f(X^{(k-1)})f_{appr}(X^{(k)})} \right) = \min \left(1, \frac{\pi_T(X^{(k-1)})}{\pi_T(X^{(k)})} \right)$$

Otherwise $X^{(k)} = X^{(k-1)}$

(3) Set $k = k + 1$ and GO TO (1)



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But we do not know $\pi_T(x)$



But we can simulate

Pseudo-marginal MH-algorithm, Andrieu and Roberts (2009)

For a given $x \in C_{a,b}([0, T])$, define a random variable S as follows:

Simulate a sequence, $Y^{(1)}, Y^{(2)}, \dots$, of independent stationary diffusions, until a sample path is obtained that intersects x

$$S = \min\{i : Y^{(i)} \text{ intersects } x\}.$$

$$E(S) = 1/\pi_T(x).$$



Pseudo-marginal Metropolis-Hastings algorithm: exact bridge

Metropolis-Hastings Markov chain with state $(X^{(k)}, S^{(k)})$.

Simulate an initial approximate (a, b, T) -diffusion bridge, $X^{(0)}$, and an associated $S^{(0)}$ (with $x = X^{(0)}$), and set $k = 1$.

(1) Propose a new sample paths by simulating an approximate (a, b, T) -diffusion bridge, $X^{(k)}$, and an associated $S^{(k)}$ (with $x = X^{(k)}$)

(2) Accept the proposed $(X^{(k)}, S^{(k)})$ with probability

$$\min \left(1, \frac{S^{(k)}}{S^{(k-1)}} \right)$$

Otherwise $X^{(k)} = X^{(k-1)}$ and $S^{(k)} = S^{(k-1)}$

(3) Set $k = k + 1$ and GO TO (1)



Multivariate diffusions and bridge simulation without discretization error

Simulation of multivariate diffusions:

Bladt, Finch and Sørensen (2016, 2021)

Uses methods from the literature on coupling of diffusion processes
(Lindvall and Rogers, 1986, Chen and Li, 1989)



Multivariate diffusions and bridge simulation without discretization error

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Diffusion bridge simulation without discretization error:

The confluent diffusion bridge sampler, by Jenkins, Pollock, Roberts and Sørensen (2021), combines two approaches

- The simple sampler of Bladt and Sørensen (2014, 2021)
- The exact and ε -strong simulation of unconditioned diffusions of Pollock, Johansen and Roberts (2016)

to obtain a sampler without discretisation error with a computing time that is linear in T



Hyperbolic diffusion

$$dX_t = -\frac{\alpha X_t}{\sqrt{1 + \|X_t\|^2}} dt + dW_t, \quad \alpha > 0$$

Data: $D = (X_{t_0}, \dots, X_{t_n})$, $t_0 = 0$

Partial observation of $\mathbf{X}_{t_n} = (X_t)_{0 \leq t \leq t_n}$



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Partial observation of $\mathbf{X}_{t_n} = (X_t)_{0 \leq t \leq t_n}$

Gibbs sampler

1. Draw α from the prior distribution
2. Simulate a sample path $\mathbf{X}_{t_n}$ conditionally on α and D
3. Draw α conditionally on $\mathbf{X}_{t_n}$ and D
4. GO TO 2



Hyperbolic diffusion

Likelihood function based on $\mathbf{X}_{t_n}$

$$L^c(\alpha) = \exp\left(\alpha H_{t_n} - \frac{1}{2}\alpha^2 B_{t_n}\right),$$

$$H_t = \sqrt{1 + \|\mathbf{X}_0\|^2} - \sqrt{1 + \|\mathbf{X}_t\|^2} + \int_0^t \frac{1 + \frac{1}{2}\|\mathbf{X}_s\|^2}{(1 + \|\mathbf{X}_s\|^2)^{3/2}} ds$$

$$B_t = \int_0^t \frac{\|\mathbf{X}_s\|^2}{1 + \|\mathbf{X}_s\|^2} ds$$

Exponential family of processes in the sense of Küchler & Sørensen (1997)



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Exponential family of processes in the sense of Küchler & Sørensen (1997)

Conjugate prior: $N_+(\bar{\alpha}, \sigma^2)$

Posterior distribution: $N_+((H_{t_n} + \bar{\alpha}/\sigma^2)/(B_{t_n} + \sigma^{-2}), (B_{t_n} + \sigma^{-2})^{-1})$

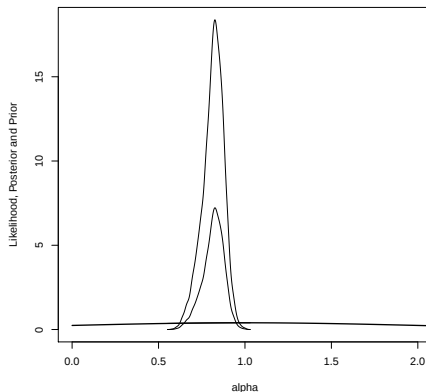


Hyperbolic diffusion

$$t_i = i, \quad i = 0, \dots, 1000$$

$\alpha = 0.8$ Prior: $N_+(1, 1)$ 5000 iterations of the Gibbs sampler

Approximative bridge simulation



Stochastic differential equation with mixed effects

Baltazar-Larios, Bladt and Sørensen (2023)

$$dX_t^i = d_{\alpha, a_i}(X_t^i)dt + \sigma_{\beta, b_i}(X_t^i)dW_t^i, \quad i = 1, \dots, N$$

$\sigma_{\beta, b}(x) > 0$ for all x, β, b , X^i ergodic

$W^i, i = 1, \dots, N$, independent standard Wiener processes

Random effect: $(a_i, b_i) \sim p_\gamma(a, b)$, $i = 1, \dots, N$,
independent random vectors

Parameters: α, β, γ

Data:

$$X_{\text{obs}} = (X_{\text{obs}}^1, \dots, X_{\text{obs}}^N)$$

$$X_{\text{obs}}^i = (X_{t_1^i}^i, \dots, X_{t_{n_i}^i}^i), \quad t_1^i < t_2^i < \dots < t_{n_i}^i, \quad i = 1, \dots, N$$



Lamperti transformation

$$dX_t^i = d_{\alpha, a_i}(X_t^i)dt + \sigma_{\beta, b_i}(X_t^i)dW_t^i, \quad i = 1, \dots, N$$

$$Y_t^i = h_{\beta, b_i}(X_t^i) \qquad h_{\beta, b}(x) = \int_{x^*}^x \frac{1}{\sigma_{\beta, b}(u)} du$$

By Ito's formula:

$$dY_t^i = \mu_{\alpha, \beta, a_i, b_i}(Y_t^i)dt + dW_t^i,$$

where

$$\mu_{\alpha, \beta, a_i, b_i}(y) = \frac{d_{\alpha, a_i}(h_{\beta, b_i}^{-1}(y))}{\sigma_{\beta, b_i}(h_{\beta, b_i}^{-1}(y))} - \frac{1}{2} \sigma'_{\beta, b_i}(h_{\beta, b_i}^{-1}(y))$$

with $\sigma'_{\beta, b_i}(x) = \partial_x \sigma_{\beta, b_i}(x)$

The probability measures corresponding to continuous time observation of Y are equivalent, and an explicit likelihood function is given by Girsanov



Data augmentation

The data X_{obs} can be thought of as a partial observation of a “full” data set $(X_{\text{obs}}, X_{\text{mis}})$

The “missing” data are $X_{\text{mis}} = (X_{\text{mis}}^1, \dots, X_{\text{mis}}^N)$ with

$$X_{\text{mis}}^i = \{Y_t^{*ij}, t \in [t_{j-1}^i, t_j^i], j = 2, \dots, n_i, a_i, b_i\}.$$

$$Y_t^{*ij} = Z_t^{ij} - \ell_{\beta, b_i}^i(t), \quad t \in [t_{j-1}^i, t_j^i]$$

$$\ell_{\beta, b}^i(t) = \frac{(t_j^i - t)h_{\beta, b}(X_{t_{j-1}^i}^i) + (t - t_{j-1}^i)h_{\beta, b}(X_{t_j^i}^i)}{t_j^i - t_{j-1}^i}, \quad t \in [t_{j-1}^i, t_j^i]$$

Conditionally on X_{obs}^i and a_i, b_i ,

$$Z_t^{ij}, \quad j = 2, \dots, n_i, \quad i = 1, \dots, N$$

are independent $(t_{j-1}^i, h_{\beta, b_i}(X_{t_{j-1}^i}^i), t_j^i, h_{\beta, b_i}(X_{t_j^i}^i))$ -bridges for the diffusion Y^i



Likelihood function for the augmented data set

$$L(\alpha, \beta, \gamma; X_{\text{obs}}, X_{\text{mis}}) = \prod_{i=1}^N L_i(\alpha, \beta; X_{\text{obs}}^i, X_{\text{mis}}^i) \prod_{i=1}^N p_\gamma(a_i, b_i)$$

where

$$\log L_i(\alpha, \beta; X_{\text{obs}}^i, X_{\text{mis}}^i) = H_{\alpha, \beta, a_i, b_i}(X_{t_n^i}^i) - H_{\alpha, \beta, a_i, b_i}(X_{t_1^i}^i)$$

$$- \sum_{j=2}^{n_i} \left[\frac{(h_{\beta, b_i}(X_{t_j^i}^i) - h_{\beta, b_i}(X_{t_{j-1}^i}^i))^2}{2(t_j^i - t_{j-1}^i)} + \log(\sigma_{\beta, b_i}(X_{t_j^i}^i)) + \frac{1}{2} \int_{t_{j-1}^i}^{t_j^i} \phi_{\alpha, \beta, a_i, b_i}(Y_s^{*ij} + \ell_{\beta, b_i}^i(s)) ds \right]$$

with

$$H_{\alpha, \beta, a, b}(x) = \int_{x^*}^x \frac{d_{\alpha, a}(u)}{\sigma_{\beta, b}^2(u)} du - \frac{1}{2} \log(\sigma_{\beta, b}(x))$$

$$\phi_{\alpha, \beta, a, b}(y) = \mu'_{\alpha, \beta, a, b}(y) + \mu_{\alpha, \beta, a, b}(y)^2$$

Girsanov plus Roberts and Stramer (2001)



Gibbs sampler

Specify a prior distribution $\pi(\alpha, \beta, \gamma)$

1. Draw (α, β, γ) from the prior distribution π
2. Conditionally on γ , draw (a_i, b_i) from p_γ , independently for $i = 1, \dots, N$
3. Simulate independent sample paths Y^{*ij} conditionally on $\alpha, \beta, a_i, b_i, X_{\text{obs}}^i$ for $j = 2, \dots, n_i$, $i = 1, \dots, N$
4. Draw (a_i, b_i) conditionally on $\alpha, \beta, \gamma, X_{\text{obs}}^i, Y^{*i2}, \dots, Y^{*in_i}$, independently for $i = 1, \dots, N$

Conditional density $\propto$

$$L_i(\alpha, \beta, \gamma; X_{\text{obs}}^i, Y^{*i2}, \dots, Y^{*in_i}, a_i, b_i) p_\gamma(a_i, b_i)$$

5. Draw (α, β, γ) given X_{mis} and X_{obs}

Conditional density $\propto \pi(\alpha, \beta, \gamma) \cdot L(\alpha, \beta, \gamma; X_{\text{obs}}, X_{\text{mis}})$

6. GO TO 3



Ornstein-Uhlenbeck with mixed effects

$$dX_t^i = -a_i X_t^i dt + \beta dW_t^i, \quad a_i \sim \text{exponential}(\gamma), \quad i = 1, \dots, N, \quad \beta > 0$$

Parameters: γ, β

Data:

$$X_{\text{obs}} = (X_{\text{obs}}^1, \dots, X_{\text{obs}}^N)$$

$$X_{\text{obs}}^i = (X_{t_1}^i, \dots, X_{t_n}^i), \quad t_1 < t_2 < \dots < t_n, \quad i = 1, \dots, N$$

Prior:

γ and β are independent

$$\gamma \sim \Gamma(\nu, \lambda^{-1}), \quad \eta = \beta^{-2} \sim \Gamma(\kappa, \delta^{-1})$$

The continuous time full model is an exponential family of processes in the sense of Küchler & Sørensen (1997)



Gibbs sampler

1. Draw (γ, η) from the prior distribution
2. $a_i \sim \text{exponential}(\gamma)$, $i = 1, \dots, N$
3. Simulate independent sample paths Y^{*ij} conditionally on $\eta, a_i, X_{\text{obs}}^i$ for $j = 2, \dots, n$, $i = 1, \dots, N$
4. $a_i \sim N_+((A_i - \gamma)/B_i, B_i^{-1})$ independently for $i = 1, \dots, N$
 $A_i = A(X_{\text{obs}}^i, \eta)$, $B_i = B(X_{\text{obs}}^i, Y^{*i}, \eta)$
5. $\gamma \sim \Gamma(\nu + N, (\lambda + a.)^{-1})$
6. $\eta \sim c\eta^{(n-N)/2+\kappa-1} e^{-\eta(E_1+\delta)} \cdot e^{\sqrt{\eta}E_2+\eta E_3}$
 $E_1 = E_1(X_{\text{obs}})$, $E_k = E_k(X_{\text{obs}}, Y^*, a_1, \dots, a_N)$, $k = 2, 3$
7. GO TO 3



Membrane potential data

Data from Picchini, De Gaetano and Ditlevsen (2010):

Membrane potential of a single neuron measured every 0.15 ms

$N = 109$ interspike intervals, $n = 1116$

Model:

$$dX_t^i = (a_i - \alpha X_t^i)dt + \beta dW_t^i, \quad a_i \sim N(\mu, \sigma^2), \quad i = 1, \dots, N,$$

Parameters: $\mu, \sigma^2 > 0, \alpha > 0, \beta > 0$

Prior:

μ, σ^2, α and β are independent

$$\mu \sim N(1, 1), \quad \tau^2 = \sigma^{-2} \sim \text{exponential}(1)$$

$$\alpha \sim \text{exponential}(1), \quad \eta = \beta^{-1} \sim \text{exponential}(1)$$



Membrane potential data

Gibbs sampler: 5000 iterations (burn-in = 4000)

Posterior distribution:

Parameter	mean	0.025-quantile	0.975-quantile
α	16.82	16.58	17.02
β	0.013513	0.013510	0.0103516
μ	0.174	0.172	0.176
σ	0.0584	0.0580	0.0593



Integrated diffusions

Baltazar-Larios and Sørensen (2010)

$$dX_t = b(X_t; \theta)dt + \sigma(X_t; \theta)dW_t, \quad X_0 \sim \nu_\theta$$

X ergodic with stationary density function ν_θ

Data:

$$Y_i = \int_{t_{i-1}}^{t_i} X_s ds + Z_i, \quad i = 1, \dots, n, \quad t_0 = 0, \quad Z_i \sim N(0, \tau^2) \text{ independent}$$

$$X_{\text{obs}} = (Y_1, \dots, Y_n)$$



Integrated diffusions

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X ergodic with stationary density function ν_θ

Data:

$$Y_i = \int_{t_{i-1}}^{t_i} X_s ds + Z_i, \quad i = 1, \dots, n, \quad t_0 = 0, \quad Z_i \sim N(0, \tau^2) \text{ independent}$$

$$X_{\text{obs}} = (Y_1, \dots, Y_n)$$

Examples: Ice-core data (paleoclimate), integrated realized volatility, molecular dynamics, harmonic oscillator

$$dV_t = -(\alpha_1 P_t + \alpha_2 V_t)dt + \sigma dW_t, \quad P_t = \int_0^t V_s ds$$

$$Y_i = P_{t_i} - P_{t_{i-1}} + Z_i$$



Integrated diffusions

Baltazar-Larios and Sørensen (2010)

$$dX_t = b(X_t; \theta)dt + \sigma(X_t; \theta)dW_t, \quad X_0 \sim \nu_\theta$$

X ergodic with stationary density function ν_θ

Data:

$$Y_i = \int_{t_{i-1}}^{t_i} X_s ds + Z_i, \quad i = 1, \dots, n, \quad t_0 = 0, \quad Z_i \sim N(0, \tau^2) \text{ independent}$$

$$X_{\text{obs}} = (Y_1, \dots, Y_n)$$

Likelihood function conditional on the diffusion process:

$$\prod_{i=1}^n \varphi \left(Y_i; \int_{t_{i-1}}^{t_i} X_s ds, \tau^2 \right), \quad \varphi \text{ Gaussian density function}$$

Data augmentation: $Y_{\text{mis}} = \{X_t : 0 \leq t \leq t_n\}$?



Likelihood function for the augmented data set

$$dX_t = b(X_t; \theta)dt + \sigma(X_t; \theta)dW_t, \quad X_0 \sim \nu_\theta$$

Lamperti transform:

$$U_t = h_\theta(X_t) \quad h_\theta(x) = \int_{x^*}^x \frac{1}{\sigma(y; \theta)} dy$$

$$Y_i = \int_{t_{i-1}}^{t_i} h_\theta^{-1}(U_s) ds + Z_i, \quad i = 1, \dots, n$$

Data augmentation: $Y_{\text{mis}} = \{U_t : 0 \leq t \leq t_n\}$

$$\log L(\theta, \tau^2; Y_1, \dots, Y_n, (U_t, t \in [0, t_n])) =$$

$$\sum_{i=1}^n \log \varphi \left(Y_i; \int_{t_{i-1}}^{t_i} h_\theta^{-1}(U_t) dt, \tau^2 \right) + H_\theta(U_{t_n}) - H_\theta(U_0) - \frac{1}{2} \int_0^{t_n} \phi_\theta(U_t) dt$$



EM algorithm

$(\hat{\theta}, \hat{\tau}^2)$ initial value of the parameter vector

(1) (E-step) Generate sample paths of $X^{(k)}$, $k = 1, \dots, M$ conditional on $Y_1, \dots, Y_n$ using the parameter value $(\hat{\theta}, \hat{\tau}^2)$, and calculate

$$g(\theta, \tau) = \frac{1}{M - M_0} \sum_{k=M_0+1}^M \log L \left(\theta, \tau; Y_1, \dots, Y_n, (h_{\hat{\theta}}(X_t^{(k)}), t \in [0, t_n]) \right)$$

(burn-in period M_0)

(2) (M-step) $(\hat{\theta}, \hat{\tau}^2) = \operatorname{argmax} g(\theta, \tau)$

(3) GO TO (1)



Conditional diffusion simulation

Chib, Pitt & Shephard (2006)

Simulate a stationary sample path of $X^{(0)}$ in $[0, t_n]$ and set $\ell = 1$

(1) Set $k_0 = 0$ and $i = 1$

(2) Draw $k_i \sim \text{Poisson}(\lambda) + 1$, if $\sum_{j=1}^i k_j \geq n$ set $k_i = n$, $K = i$ and stop, else set $i = i + 1$ and repeat 2

(3) For $j = 1, \dots, K$ simulate independent $(X_{t_{k_{j-1}}}^{(\ell-1)}, X_{t_{k_j}}^{(\ell-1)}, t_{k_j} - t_{k_{j-1}})$ -bridges $B^{(\ell,j)}$ conditional on $Y_{t_{k_{j-1}}+1}, \dots, Y_{t_{k_j}}$ and set

$$X_t^{(\ell)} = B_{t-t_{k_{j-1}}}^{(\ell,j)} \text{ for } t \in [t_{k_{j-1}}, t_{k_j}], j = 1, \dots, K$$

(4) Set $\ell = \ell + 1$ and GO TO (1)



Conditional bridge simulation

The following Metropolis-Hastings algorithm simulates the $(X_{t_{k_{j-1}}}^{(\ell-1)}, X_{t_{k_j}}^{(\ell-1)}, t_{k_j} - t_{k_{j-1}})$ -bridge $B^{(\ell,j)}$ conditional on $Y_{k_{j-1}+1}, \dots, Y_{k_j}$:

(1) Simulate an initial $(X_{t_{k_{j-1}}}^{(\ell-1)}, X_{t_{k_j}}^{(\ell-1)}, t_{k_j} - t_{k_{j-1}})$ -diffusion bridge, $B^{(\ell,j,0)}$, and set $k = 1$.

(2) Propose a new sample path by sampling a $(X_{t_{k_{j-1}}}^{(\ell-1)}, X_{t_{k_j}}^{(\ell-1)}, t_{k_j} - t_{k_{j-1}})$ -diffusion bridge $B^{(\ell,j,k)}$

(3) Accept the proposed diffusion bridge with probability

$$\min \left(1, \prod_{i=k_{j-1}+1}^{k_j} \frac{\varphi \left(Y_i; \int_{t_{i-1}}^{t_i} B_{t-t_{k_{j-1}}}^{(\ell,j,k)} dt, \tau^2 \right)}{\varphi \left(Y_i; \int_{t_{i-1}}^{t_i} B_{t-t_{k_{j-1}}}^{(\ell,j,k-1)} dt, \tau^2 \right)} \right).$$

Otherwise $B^{(\ell,j,k)} = X^{(\ell,j,k-1)}$

(4) Set $k = k + 1$ and GO TO (2)



Integrated square root process: simulation study

$$dX_t = (\alpha - \beta X_t)dt + \sigma \sqrt{X_t}dW_t$$

$$\alpha = 0.5 \quad \beta = 0.2 \quad \sigma = 0.5 \quad \tau^2 = 1.25$$

$$Y_i, \quad t_i = i, \quad i = 1, \dots, 1500$$

$$M = 10000, \quad M_0 = 1000$$

1000 simulated datasets

Average of parameter estimates:

λ	α	β	σ	τ^2
30	0.4802	0.2056	0.4787	1.2432
20	0.4727	0.2043	0.4698	1.2406
10	0.4587	0.1965	0.4609	1.2287



Ice core data

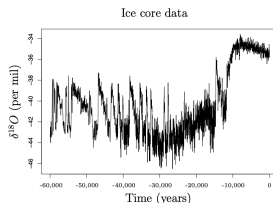


Figure 6.1: $\delta^{18}O$ -values integrated over 20 years intervals obtained from ice core data from the Greenland ice-sheet.

Model:

$$dX_t = -\alpha X_t dt + \sigma dW_t$$

EM-algorithm: $M = 10000$, $M_0 = 1000$ $\lambda = 20$

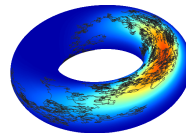
Parameter	[-10000,0]	[-30000,-10000]	[-60000,-30000]
α^{-1}	205.3	669.8	321.1
σ	0.0303	0.1167	0.1395
$\sigma / \sqrt{2\alpha}$	0.307	2.136	1.767
τ^2	0.1063	0.6967	0.2260

Ditlevsen, Ditlevsen and Andersen (2002)

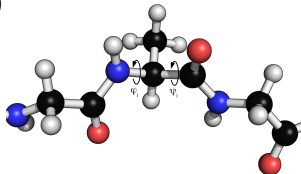


Model of protein structure evolution

García-Portugués and Sørensen (2023)



Dihedral angles (ϕ, ψ)



A simplified representation of a protein of size N is

$$\begin{array}{c} \text{Protein Structure} \end{array} = ((\phi, \psi), \mathbf{a}, \mathbf{s}) \in \underbrace{\mathbb{T}^{2N}}_{\text{dihedral angles}} \times \underbrace{\{1, \dots, 20\}^N}_{\text{amino acids}}$$

The stochastic process (ϕ_t, ψ_t) must be *ergodic*, *time-reversible* and *reasonably tractable*



New circular diffusions

$f : \mathbb{R} \rightarrow \mathbb{R}^+$ is a differentiable **circular** probability density:

(i) $f(x + 2k\pi) = f(x)$ and (ii) $\int_0^{2\pi} f(\theta) d\theta = 1$, for any $x \in \mathbb{R}$ and $k \in \mathbb{Z}$

$F(x) = \int_0^x f(\theta) d\theta$, $x \in \mathbb{R}$, is a one-to-one map $\mathbb{R} \rightarrow \mathbb{R}$

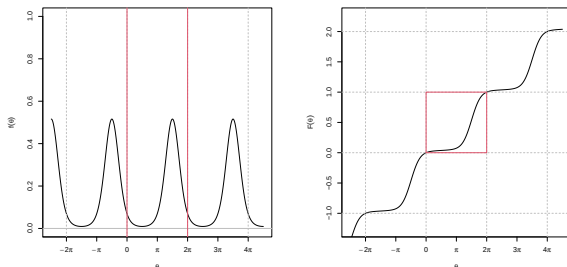


Figure: Circular pdf f (left) and its cdf F (right), with extensions from $[0, 2\pi)$ (red boundaries) to $\mathbb{R}$.



New circular diffusions

Define $\Theta_t = F^{-1}(\sigma W_t + F(\theta_0)) \bmod 2\pi$, $t > 0$,

where W is a standard Wiener process, $\sigma > 0$ and $\theta_0 \in [0, 2\pi)$

Proposition

- ① $\{\Theta_t\}$ solves the SDE

$$d\Theta_t = -\frac{\sigma^2 f'(\Theta_t)}{2f(\Theta_t)^3} dt + \frac{\sigma}{f(\Theta_t)} dW_t$$

on the circle $\mathbb{T}^1 := [0, 2\pi)$, with 0 and 2π identified

- ② $\{\Theta_t\}$ is time-reversible and ergodic with stationary density f
- ③ For $t > 0$ and $\theta_1, \theta_2 \in \mathbb{T}^1$, the transition density of $\{\Theta_t\}$ is

$$p_t(\theta_2 | \theta_1) = 2\pi f_{\text{WN}}(2\pi F(\theta_2); 2\pi F(\theta_1), 4\pi^2 t \sigma^2) f(\theta_2),$$

where $f_{\text{WN}}(\theta; \mu, \sigma^2) = \sum_{k \in \mathbb{Z}} \phi_{\sigma^2}(\theta - \mu + 2k\pi)$ is the **wrapped normal** density function, with $\phi_{\sigma^2}(\cdot)$ denoting the density of $\mathcal{N}(0, \sigma^2)$

$$\Theta_{t_2} | \Theta_{t_1} = \theta_1 \sim p_{t_2 - t_1}(\cdot | \theta_1), \quad t_2 > t_1 \geq 0$$



Example: a von Mises diffusion

The von Mises distribution has the density function

$$f_{\text{vM}}(\theta; \mu, \kappa) = (2\pi I_0(\kappa))^{-1} \exp\{\kappa \cos(\theta - \mu)\}, \quad \mu \in \mathbb{T}^1, \quad \kappa > 0$$

The von Mises diffusion solves the SDE

$$d\Theta_t = \frac{\sigma^2 \kappa \sin(\Theta_t - \mu)}{2 \exp\{\kappa \cos(\Theta_t - \mu)\}} dt + \frac{\sigma}{\exp\{\kappa \cos(\Theta_t - \mu)\}} dW_t$$



Example: a von Mises diffusion

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The von Mises diffusion solves the SDE

$$d\Theta_t = \frac{\sigma^2 \kappa \sin(\Theta_t - \mu)}{2 \exp\{2\kappa \cos(\Theta_t - \mu)\}} dt + \frac{\sigma}{\exp\{\kappa \cos(\Theta_t - \mu)\}} dW_t$$

Experiment: Assessing directionality of ants movement. An ant in a circular container, movement tracked for 2 x 10 minutes

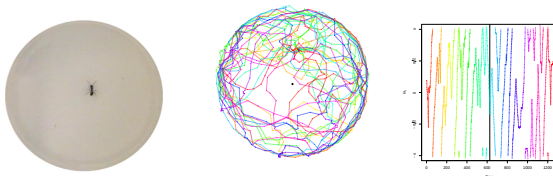


Figure: Ant, recorded track, and the track's angles



Experiment: assessing directionality of ants movement

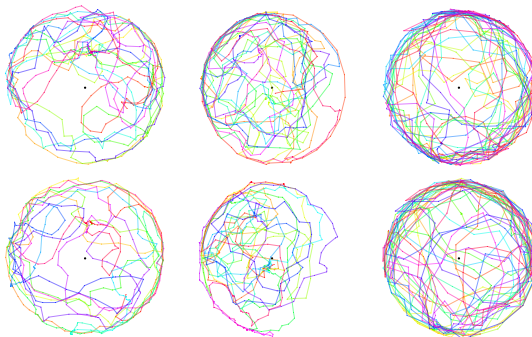


Figure: Rows: “exploration” and “revisit” stages. Columns: three most active ants

Same directional behaviour in “exploration” and “revisit” stages?

$$\mathcal{H}_0 : \xi_{\text{exp.}} = \xi_{\text{rev.}} \text{ vs. } \mathcal{H}_1 : \xi_{\text{exp.}} \neq \xi_{\text{rev.}}, \quad \xi = (\mu, \kappa, \sigma)$$

Ant 1, 2, 3 homogeneity p -values: 0.1394, 1.4×10^{-14} , 9.1×10^{-12}

